AMENDMENTS TO THE SPECIFICATION:

Please replace paragraph **[045]** with the following amended paragraph:

[045] [A] The feeding area 544 adjacent to cultivation area 542 is comprised of a feed trough [[area]] 548 comprising sloped floors 512 that slope downward to a centrally disposed elongated opening 513 covered by a perforated cover 518 (partially removed to show opening 513). The sloped floors 512, opening 513 and perforated cover 518 are analogous to components that comprise the feed trough 11 of FIGs. 2A and 2B. However, in the embodiment of FIG. 5 and 6 the sloped floors 512 are molded into and integral with floor 507 of container 510. Apart from the area so occupied by feed trough [[area]] 548, feeding area 544 also is comprised of two sections of floor 507 separated by a feeding area ramp 550. The feeding area ramp 550 slopes downward to an adjacent part of sloped floors 512, permitting easier access for frogs to enter and/or remain next to the feed trough [[area]] 548.

Please replace paragraph **[053]** with the following amended paragraph:

[053] More generally, a vibrator also may be the sole means for moving feed particles in a feed collection area to simulate live feed movement to stimulate feeding in the amphibians in the cultivation container. The vibrator may operate to continue to move feed particles even as food particles collect[[ion]] in one or more areas of the floor that are low relative to other areas. Alternatively, a vibrator may be used in combination with any device that is able to propel or otherwise redistribute feed particles to a higher part of the floor of the feed collection area. Thus, a means for moving feed particles in a feed collection area may include, but is not limited to, propelling feed particles using an airflow through a perforated cover (with or without vibrating feed particles that are on the floor of the feed collection area), and vibrating feed particles that are on the floor of the feed collection area. Accordingly, air, vibrational, or other force known to those skilled in the part, or later developed, is provided to move the feed particles within the container, particularly in the feed collection area, to simulate live feed and thereby stimulate feeding behavior and achieve feeding.